

# Applied Mathematics Qualifying Exam

September 21, 2023

Time limit: 2.5 hours

**Instructions:** This exam has three parts A, B, and C, each of which contains three problems. Choose TWO problems from each of Parts A and C, and in Part B, you MUST do Problem 1 and then choose ONE of problems 2 and 3, for a total of SIX problems.

## Part A

Choose any TWO of the following problems.

1. Consider the planar ODE

$$\begin{aligned}u' &= v \\v' &= 2v - u(1 - u)^2.\end{aligned}\tag{1}$$

- (a) Find the linearization of (1) at the fixed points  $p_0 = (0, 0)$  and  $p_1 = (1, 0)$ .
- (b) Show that the triangular region  $\mathcal{T}$  bounded by the lines  $v = 0$ ,  $u = 1$ , and  $v = u$ , is negatively invariant under the flow of (1).
- (c) Show that (1) admits a heteroclinic orbit between the fixed points  $p_0$  and  $p_1$  which approaches  $p_1$  along a center manifold.

2. Consider the boundary value problem

$$\begin{aligned}\varepsilon y'' + a(x)y' + b(x)y &= 0, & 0 < x < 1 \\y(0) &= y_0, & y(1) &= y_1,\end{aligned}$$

where  $a(x) > 0$  for  $x \in [0, 1]$ . Using WKB theory, show that a leading order asymptotic expansion for the solution is given by

$$y(x) \sim C_1 e^{-\int_0^x (b(s)/a(s)) ds} + \frac{C_2}{a(x)} e^{\int_0^x (b(s)/a(s)) ds - \frac{1}{\varepsilon} \int_0^x a(s) ds}$$

where

$$C_1 = y_1 e^{\int_0^1 (b(s)/a(s)) ds}, \quad \text{and} \quad C_2 = a(0)(y_0 - C_1).$$

3. Consider the initial value problem

$$\dot{u} = f(u), \quad u(0) = u_0. \quad (2)$$

where  $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is locally Lipschitz. That is, there exists  $K, \delta > 0$  such that  $|f(u) - f(v)| \leq K|u - v|$  for all  $u, v \in B_\delta(u_0) = \{u \in \mathbb{R}^n : |u - u_0| < \delta\}$ .

(a) Consider the map  $T$  defined by

$$(Tu)(t) = u_0 + \int_0^t f(u(s)) ds.$$

and take  $\varepsilon < \min\{\frac{1}{K}, \frac{\delta}{M}\}$  where  $M = \sup_{u \in B_\delta(u_0)} |f(u)|$ . Show that  $T$  is a contraction on the space  $\mathcal{B} = \{u \in C^0([-\varepsilon, \varepsilon], \mathbb{R}^n) : \sup_{t \in [-\varepsilon, \varepsilon]} |u(t) - u_0| < \delta\}$ , where  $C^0([-\varepsilon, \varepsilon], \mathbb{R}^n)$  denotes the space of continuous functions with the supremum norm  $\|u\| = \sup_{t \in [-\varepsilon, \varepsilon]} |u(t)|$ . What does this imply about solutions to the initial value problem (2)? (You may use the contraction mapping theorem without proof.)

(b) Now suppose  $f \in C^1(\mathbb{R}^n)$  and that the maximal interval of existence of the solution to the initial value problem (2) is  $(-\infty, \beta)$  where  $\beta < \infty$ . Show that  $|u(t)|$  is unbounded as  $t \rightarrow \beta$ .

## Part B

You must complete problem 1, and then choose ONE of problems 2 or 3.

1. (**Mandatory**) Numerical ODE problem.

Consider a linear multistep scheme of the form

$$\begin{aligned} w_{n+1} &= a_1 w_n + a_2 w_{n-1} + h(b_0 f(t_{n+1}, w_{n+1}) + b_1 f(t_n, w_n)), \quad n \geq 1, \\ w_1 &= y_1, \\ w_0 &= y_0, \end{aligned}$$

for solving the ODE:  $y' = f(t, y)$  for  $0 < t \leq T$  and  $y(0) = y_0$ . Here,  $h = T/N$  is the time step,  $N$  is the total number of time steps,  $t_n = nh$  and  $\mathbf{w}_n$  is the numerical approximation to  $\mathbf{y}(t)$  at  $t = t_n$ .

- Find the equation for the error  $\mathbf{e}_n = \mathbf{y}_n - \mathbf{w}_n$ , e.g., that describes how the error propagates in time, and describe the meaning of each of the terms in the equation.
- What is the highest order of accuracy this method can attain? Determine the coefficients  $a_1, a_2, b_0, b_1$  that make the scheme reach this order of accuracy, assuming  $y_1$  is a sufficiently accurate approximation of  $y(h)$ . **Hint:** The scheme is  $p$ th order accurate if the test functions  $y(t) = 1, t, t^2, \dots, t^p$ , and  $f(t, y(t)) = 0, 1, 2t, \dots, pt^{p-1}$  satisfy the scheme exactly with  $h = 1$ .
- How do you determine if the method is stable? Hint: Don't forget that this is a multistep method.
- Define  $A$ -stability for a numerical scheme for first order ODEs. Is the optimally accurate scheme you found  $A$ -stable?

2. Least squares problem.

- (a) Let  $A$  be a real  $m \times n$  matrix. State the singular value decomposition (SVD) of  $A$ . Briefly present an algorithm to solve the overdetermined system ( $m > n$ ) using the SVD.
- (b) What are the advantages and disadvantages of using the SVD to solve overdetermined systems?

(c) Perform the SVD on the matrix  $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{pmatrix}$ .

- (d) Compute the pseudo-inverse of  $A$  (the Moore-Penrose pseudo-inverse). Leave in factored form.

(e) Find the minimal length, least squares solution of the problem:  $A\mathbf{x} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ .

3. Eigenvalue problem.

- (a) Let  $A$  be a  $n \times n$  matrix. Prove Gerschgorin's theorem, which states: For  $i = 1, \dots, n$  let  $R_i = \sum_{\substack{j=1 \\ j \neq i}}^n |a_{ij}|$ . Every eigenvalue of  $A$  falls within at least one of the closed discs in the complex plane with center at  $a_{ii}$  and radius  $R_i$ . **Hint:** Let

$$A\mathbf{x} = \lambda\mathbf{x} \tag{3}$$

and assume that the largest component of  $\mathbf{x}$  in absolute value is  $x_k$ . Consider the  $k$ th equation of Eq. (3).

- (b) Consider the matrix  $A = \begin{pmatrix} 2 & -1 & 0 & 0 & 0 \\ -1 & 2 & -1 & 0 & 0 \\ 0 & -1 & 2 & -1 & 0 \\ 0 & 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & -1 & 2 \end{pmatrix}$ . Show that  $A$  is positive definite.

**Hint:** Use Gerschgorin's theorem to show that  $A$  is positive semi-definite. Then consider the equation where  $A\mathbf{x} = \mathbf{0}$ , where the first component of  $\mathbf{x}$  equals 1.

- (c) Let  $A = \begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}$ . Find the eigenvalues of  $A$  and verify that Gerschgorin's theorem holds.

## Part C

Choose any TWO of the following problems.

1. Let  $g : \mathbb{R} \rightarrow \mathbb{R}$  be given by  $g(v) = v[1 + \min\{v, 0\}]$ .

(a) Show that  $g$  is convex, continuously differentiable, and satisfies

$$g(v) \geq \max\{v, |v| - 1\}.$$

(b) Deduce that any arc  $x$  admissible for the problem

$$\min J(x) = \int_0^1 (x^2 + g(x')) dt :$$

subject to  $x \in \text{AC}[0, 1], x(0) = 0, x(1) = 1$  satisfies  $J(x) > 1$ .

(c) Show that the functions

$$x_i(t) = \begin{cases} 0 & \text{if } 0 \leq t \leq 1 - 1/i \\ i[t - 1 + 1/i] & \text{if } 1 - 1/i < t \leq 1 \end{cases}$$

satisfy  $\lim_{i \rightarrow \infty} J(x_i) \rightarrow 1$ .

(d) Conclude that the problem defined in (b) admits no solution.

2. Assume  $f \in L^2(\Omega)$ .

(a) Prove the dual variational principle that

$$\min_{v \in H_0^1(\Omega)} \int_{\Omega} \left( \frac{1}{2} |\nabla v|^2 - fv \right) dx = \max_{\substack{\sigma \in L^2(\Omega; \mathbb{R}^n) \\ \text{div } \sigma = f}} -\frac{1}{2} \int_{\Omega} |\sigma|^2 dx.$$

(b) Write out Euler-Lagrange equations for both formulations.

3. For each of the given Lagrangian, find the Hamiltonian and solve the Hamiltonian system.

(a)  $L(t, x, v) = (v + kx)^2, k \neq 0$ .

(b)  $L(t, x, v) = e^{-x} \sqrt{1 + v^2}$ .